

CHARACTERIZING FIBRE REINFORCEMENT THROUGH SURFACE WRINKLES

Author: Artur L. Gower Supervisor: Prof. Michel Destrade

National University of Ireland Galway



Fibre Reinforced Tissues (one preferred direction)



Figure: Smooth muscles cells cut along the cells and cross section.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Fibre Reinforced Tissues (one preferred direction)



Figure: Smooth muscles cells cut along the cells and cross section.



Figure: Sciatic nerve cells cut along the cells and cross section. = -20

Phenomena on a larger scale.



・ロト ・個ト ・モト ・モト

æ

Phenomena on a larger scale.



Potential energy $W = W(I_1, I_2, I_3, I_4, I_5)$

$$\begin{split} &l_1 = \mathrm{tr} \mathbf{C}, \quad l_2 = (\mathrm{tr} \mathbf{C})^2 / 2 - \mathrm{tr} (\mathbf{C}^2) / 2, \quad l_3 = \det \mathbf{C}, \\ &l_4 = \mathbf{M}^T \mathbf{C} \mathbf{M}, \quad l_5 = \mathbf{M}^T \mathbf{C}^2 \mathbf{M}, \end{split}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

where $\mathbf{C} = \mathbf{F}^T \mathbf{F}$ and $\mathbf{F} = \nabla \chi(X)$.

For convenience I_5 is often dropped so $W = W(I_1, I_2, I_3, I_4)$, however in this case

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

For convenience I_5 is often dropped so $W = W(I_1, I_2, I_3, I_4)$, however in this case

■ Shearing modes are coupled, which is not supported by experiments [Murphy, 2013].

For convenience I_5 is often dropped so $W = W(I_1, I_2, I_3, I_4)$, however in this case

■ Shearing modes are coupled, which is not supported by experiments [Murphy, 2013].

■ It is unlikely to reproduce certain tensile experiments [Destrade et al., 2013].

For convenience I_5 is often dropped so $W = W(I_1, I_2, I_3, I_4)$, however in this case

■ Shearing modes are coupled, which is not supported by experiments [Murphy, 2013].

■ It is unlikely to reproduce certain tensile experiments [Destrade et al., 2013].

■ Unlikely universal relations are created [Pucci and Saccomandi, 2014].

For convenience I_5 is often dropped so $W = W(I_1, I_2, I_3, I_4)$, however in this case

■ Shearing modes are coupled, which is not supported by experiments [Murphy, 2013].

■ It is unlikely to reproduce certain tensile experiments [Destrade et al., 2013].

■ Unlikely universal relations are created [Pucci and Saccomandi, 2014].

So let's hang on to both I_4 and I_5 .

There are many choices for how to include the anisotropic invariants in *W*, for example [Holzapfel and Ogden, 2010, Lu and Zhang, 2005], [Ciarletta et al., 2011, Horgan and Saccomandi, 2005].

There are many choices for how to include the anisotropic invariants in *W*, for example [Holzapfel and Ogden, 2010, Lu and Zhang, 2005], [Ciarletta et al., 2011, Horgan and Saccomandi, 2005].

■ Most focus on how the fibres resist extension.

There are many choices for how to include the anisotropic invariants in *W*, for example [Holzapfel and Ogden, 2010, Lu and Zhang, 2005], [Ciarletta et al., 2011, Horgan and Saccomandi, 2005].

■ Most focus on how the fibres resist extension.

■ [Ciarletta et al., 2011] note that fibers also alter the mechanical response when under compression at the macroscopic and the microscopic levels.

There are many choices for how to include the anisotropic invariants in *W*, for example [Holzapfel and Ogden, 2010, Lu and Zhang, 2005], [Ciarletta et al., 2011, Horgan and Saccomandi, 2005].

■ Most focus on how the fibres resist extension.

■ [Ciarletta et al., 2011] note that fibers also alter the mechanical response when under compression at the macroscopic and the microscopic levels.

How about clearly separating the influence of both invariants?

There are many choices for how to include the anisotropic invariants in *W*, for example [Holzapfel and Ogden, 2010, Lu and Zhang, 2005], [Ciarletta et al., 2011, Horgan and Saccomandi, 2005].

■ Most focus on how the fibres resist extension.

■ [Ciarletta et al., 2011] note that fibers also alter the mechanical response when under compression at the macroscopic and the microscopic levels.

How about clearly separating the influence of both invariants?

How about modelling fibre resistance to compression?

We can rewrite I_5 ,

We can rewrite I_5 ,

$$C^{3} - C^{2} l_{1} + C l_{2} - I l_{3} = 0 \implies C^{2} - C l_{1} + I l_{2} - C^{-1} l_{3} = 0,$$

We can rewrite I_5 ,

$$\mathbf{C}^3 - \mathbf{C}^2 l_1 + \mathbf{C} l_2 - \mathbf{I} l_3 = \mathbf{0} \implies \mathbf{C}^2 - \mathbf{C} l_1 + \mathbf{I} l_2 - \mathbf{C}^{-1} l_3 = \mathbf{0},$$

contracting $\mathbf{M}^{\mathcal{T}}$ on the left and \mathbf{M} on the right

$$I_5 = \mathbf{M}^T \mathbf{C}^2 \mathbf{M} = I_4 I_1 - I_2 + \mathbf{M}^T \mathbf{C}^{-1} \mathbf{M} I_3.$$

(ロ)、(型)、(E)、(E)、 E) の(の)

We can rewrite I_5 ,

$$\mathbf{C}^3 - \mathbf{C}^2 l_1 + \mathbf{C} l_2 - \mathbf{I} l_3 = \mathbf{0} \implies \mathbf{C}^2 - \mathbf{C} l_1 + \mathbf{I} l_2 - \mathbf{C}^{-1} l_3 = \mathbf{0},$$

contracting $\mathbf{M}^{\mathcal{T}}$ on the left and \mathbf{M} on the right

$$I_5 = \mathbf{M}^T \mathbf{C}^2 \mathbf{M} = I_4 I_1 - I_2 + \mathbf{M}^T \mathbf{C}^{-1} \mathbf{M} I_3.$$

So instead of I_4 and I_5 we can use

$$I_4^S = I_4 = \mathbf{M}^T \mathbf{C} \mathbf{M}$$
 and $I_4^C = \mathbf{M}^T \mathbf{C}^{-1} \mathbf{M}$.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへで

We can rewrite I_5 ,

$$\mathbf{C}^3 - \mathbf{C}^2 l_1 + \mathbf{C} l_2 - \mathbf{I} l_3 = \mathbf{0} \implies \mathbf{C}^2 - \mathbf{C} l_1 + \mathbf{I} l_2 - \mathbf{C}^{-1} l_3 = \mathbf{0},$$

contracting $\mathbf{M}^{\mathcal{T}}$ on the left and \mathbf{M} on the right

$$I_5 = \mathbf{M}^T \mathbf{C}^2 \mathbf{M} = I_4 I_1 - I_2 + \mathbf{M}^T \mathbf{C}^{-1} \mathbf{M} I_3$$

So instead of I_4 and I_5 we can use

$$I_4^S = I_4 = \mathbf{M}^T \mathbf{C} \mathbf{M}$$
 and $I_4^C = \mathbf{M}^T \mathbf{C}^{-1} \mathbf{M}$.

Clear interpretation, for example $W = W(I_4^S, I_4^C)$

$$\boldsymbol{\sigma} = 2\partial_{l_4^S} W\mathbf{m}^S \otimes \mathbf{m}^S - 2\partial_{l_4^C} W\mathbf{m}^C \otimes \mathbf{m}^C,$$

with $\mathbf{m}^{S} = \mathbf{F}\mathbf{M}$ and $\mathbf{m}^{C} = \mathbf{F}^{-T}\mathbf{M}$.

Prototype:

$$W_A = \frac{A_S}{4}(I_4^S - 1)^2 + \frac{A_C}{4}(I_4^C - 1)^2.$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Prototype:

$$W_A = rac{A_S}{4}(I_4^S - 1)^2 + rac{A_C}{4}(I_4^C - 1)^2.$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

Example for $F_{ij} = \lambda M_i M_j + \lambda^{-1} M_i^{\perp} M_j^{\perp}$,

Prototype:

$$W_A = \frac{A_S}{4}(I_4^S - 1)^2 + \frac{A_C}{4}(I_4^C - 1)^2.$$

Example for $F_{ij} = \lambda M_i M_j + \lambda^{-1} M_i^{\perp} M_j^{\perp}$,



Figure: $\mathbf{M}^T \boldsymbol{\sigma} \mathbf{M} = \sigma_m$ with $A_S = \cos \tau$ and $A_C = \sin \tau$.

Determining the model's parameters from experiments is a major challenge when using both anisotropic invariants.

(ロ)、(型)、(E)、(E)、 E) のQの

Determining the model's parameters from experiments is a major challenge when using both anisotropic invariants.

Surface wrinkles can assist in characterizing the material.

Determining the model's parameters from experiments is a major challenge when using both anisotropic invariants.

Surface wrinkles can assist in characterizing the material.

Changing the contribution of I_4^S vs I_4^C should significantly alter the resulting wrinkles.

Surface Wrinkles

We look for
$$\delta \chi(x_1, x_2, x_3) = \mathbf{U}(x_2) \mathrm{e}^{\mathrm{i}k(x_2 \cos \theta + x_3 \sin \theta)}$$
, $\mathbf{x} = \chi(X)$

Surface Wrinkles

We look for
$$\delta \chi(x_1, x_2, x_3) = \mathbf{U}(x_2) \mathrm{e}^{\mathrm{i}k(x_2 \cos \theta + x_3 \sin \theta)}$$
, $\mathbf{x} = \chi(X)$



Figure: A surface-wrinkle with $\mathbf{n} = (\cos \theta, 0, \sin \theta)$. The surface-wrinkle's amplitude decays as x_2 increases. (Show gif of a wrinkle forming, more technical see [Gower, 2014])

Surface Wrinkles

We look for
$$\delta \chi(x_1, x_2, x_3) = \mathbf{U}(x_2) \mathrm{e}^{\mathrm{i}k(x_2 \cos \theta + x_3 \sin \theta)}$$
, $\mathbf{x} = \chi(X)$



Figure: A surface-wrinkle with $\mathbf{n} = (\cos \theta, 0, \sin \theta)$. The surface-wrinkle's amplitude decays as x_2 increases. (Show gif of a wrinkle forming, more technical see [Gower, 2014])



Figure: A schematic of the shear-box deformation.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ



▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣 ● ○ Q Q





Surface Wrinkle Results

Incompressible
$$W = I_1 + \frac{A_S}{4}(I_4^S - 1)^2 + \frac{A_C}{4}(I_4^C - 1)^2$$
.



(日)、

э

Figure: Critical deformation ϕ^* and wrinkle-front angle θ^* with $(A_S, A_C) = 16(\cos \tau, \sin \tau)$ and $\tau = 0^\circ$, 45° and 90°.

Surface Wrinkle Results

Incompressible
$$W = I_1 + \frac{A_S}{4}(I_4^S - 1)^2 + \frac{A_C}{4}(I_4^C - 1)^2$$
.



Figure: Critical deformation ϕ^* and wrinkle-front angle θ^* with $(A_S, A_C) = 16(\cos \tau, \sin \tau)$ and $\tau = 0^\circ$, 45° and 90°.

Might be simpler to investigate with either $A_S = 0$ or $A_C = 0$.



Figure: Both A_S and A_C take the values 16, 32 and 64. The solid black line $\phi^* = 50.75^\circ$ for $A_S = A_C = 0$.

To understand the wrinkle wavefront angle θ we need the angles α_S and α_C that

$$\mathbf{m}^{S} = \mathbf{F}\mathbf{M}$$
 and $\mathbf{m}^{C} = \mathbf{F}^{-T}\mathbf{M}$

(日)、

э

make with the x_1 -axis.



Figure: Both A_S and A_C take the values 16, 32 and 64. The solid black line $\phi^* = 50.75^\circ$ for $A_S = A_C = 0$.

To understand the wrinkle wavefront angle θ we need the angles $\alpha_{\rm S}$ and $\alpha_{\rm C}$ that

$$\mathbf{m}^S = \mathbf{F}\mathbf{M}$$
 and $\mathbf{m}^C = \mathbf{F}^{-T}\mathbf{M}$
make with the x_1 -axis. ($I_4^S = \|\mathbf{m}^S\|^2$ and $I_4^C = \|\mathbf{m}^C\|^2$)



Figure: The dashed lines are either $\theta^* - \alpha_S = 90^\circ$, 33.3° or -33.3°. The solid black line is given by $\theta^* = 109.6^\circ$ and is the wrinkle-front angle if there were no fibres.



Figure: The dashed lines are either $\theta^* - \alpha_S = 90^\circ$, 33.3° or -33.3°. The solid black line is given by $\theta^* = 109.6^\circ$ and is the wrinkle-front angle if there were no fibres.

(日)、



Figure: The dashed lines are either $\theta^* - \alpha_S = 0^\circ$, 55° or -55°. The solid black line is given by $\theta^* = 109.6^\circ$ and is the wrinkle-front angle if there were no fibres.

(日)、

э



Figure: The dashed lines are either $\theta^* - \alpha_S = 0^\circ$, 55° or -55°. The solid black line is given by $\theta^* = 109.6^\circ$ and is the wrinkle-front angle if there were no fibres.

Adding nonlinearity (Mooney-Rivlin) to the soft matrix does alter the phenomena.

(ロ)、

Adding nonlinearity (Mooney-Rivlin) to the soft matrix does alter the phenomena. How about $A_S = A_C = 32$,



Figure: The dashed lines are either $\theta^* - \alpha_C = 0^\circ$, 90° , $33.3^\circ/2 + 55^\circ/2$ or $-33.3^\circ/2 - 55^\circ/2$.

To what extent does this *quanta* phenomena occur? Let's run some experiments for

To what extent does this *quanta* phenomena occur? Let's run some experiments for **I** non-zero surface stress



Red: $(A_S, A_C) = (32, 0), \alpha = \alpha_S,$ Blue: $(A_S, A_C) = (0, 32), \alpha = \alpha_C$ with surface stress. To what extent does this *quanta* phenomena occur? Let's run some experiments for \blacksquare non-zero surface stress \blacksquare using I_5 in place of I_4^C



Red: $(A_{S}, A_{C}) = (32, 0), \alpha = \alpha_{S},$ Blue: $(A_{S}, A_{C}) = (0, 32), \alpha = \alpha_{S}$ with I_{5} . To what extent does this *quanta* phenomena occur? Let's run some experiments for \blacksquare non-zero surface stress \blacksquare using I_5 in place of I_4^C \blacksquare remove incompressibility



Red: $(A_{S}, A_{C}) = (32, 0), \alpha = \alpha_{S},$ Blue: $(A_{S}, A_{C}) = (0, 32), \alpha = \alpha_{C}.$

▲ロト ▲御 ト ▲ 臣 ト ▲ 臣 ト の Q @

To what extent does this *quanta* phenomena occur? Let's run some experiments for \blacksquare non-zero surface stress \blacksquare using I_5 in place of I_4^C \blacksquare remove incompressibility \blacksquare only planar θ^*



Red: $(A_{S}, A_{C}) = (32, 0), \alpha = \alpha_{S},$ Blue: $(A_{S}, A_{C}) = (0, 32), \alpha = \alpha_{C}.$

■ In general wrinkles align with Fibres or orthogonal, analytic constraints...

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

■ In general wrinkles align with Fibres or orthogonal, analytic constraints...

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Other quanta not well understood.

■ In general wrinkles align with Fibres or orthogonal, analytic constraints...

Other quanta not well understood.

Use numerical experiments to guide more analytical results.

■ In general wrinkles align with Fibres or orthogonal, analytic constraints...

- Other quanta not well understood.
- Use numerical experiments to guide more analytical results.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Use asymptotics to get quick results.

■ In general wrinkles align with Fibres or orthogonal, analytic constraints...

■ Other quanta not well understood.

Use numerical experiments to guide more analytical results.

Use asymptotics to get quick results.

■ With simply quick results we can look to characterize the material through the surface wrinkles.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

■ In general wrinkles align with Fibres or orthogonal, analytic constraints...

- Other quanta not well understood.
- Use numerical experiments to guide more analytical results.
- Use asymptotics to get quick results.
- With simply quick results we can look to characterize the material through the surface wrinkles.



Any questions?

Thanks for listening and I hope you enjoyed the talk!

Brangwynne, C. P., MacKintosh, F. C., Kumar, S., Geisse, N. A., Talbot, J., Mahadevan, L., Parker, K. K., Ingber, D. E., and Weitz, D. A. (2006).

Microtubules can bear enhanced compressive loads in living cells because of lateral reinforcement.

Journal of Cell Biology.

- Ciarletta, P., Izzo, I., Micera, S., and Tendick, F. (2011).
 Stiffening by fiber reinforcement in soft materials: A hyperelastic theory at large strains and its application.
 - J. Biomech. Behavior Biomed. Mat., 4:1359–1368.
 - Destrade, M., Donald, B. M., Murphy, J. G., and Saccomandi, G. (2013).

At least three invariants are necessary to model the mechanical response of incompressible, transversely isotropic materials. *Computational Mechanics*, 52(4):959–969.

Gower, A. L. (2014).

Characterizing fibre reinforced elastic solids through the formation of surface wrinkles.

submitted.

Holzapfel, G. a. and Ogden, R. W. (2010). Constitutive modelling of arteries.

Proceedings of the Royal Society A: Mathematical, Physical and Engineering Sciences, 466(2118):1551-1597.

Horgan, C. O. and Saccomandi, G. (2005). A new constitutive theory for fiber-reinforced incompressible nonlinearly elastic solids.

Journal of the Mechanics and Physics of Solids, 53(9):1985-2015.

- Lu, J. and Zhang, L. (2005).

Physically motivated invariant formulation for transversely isotropic hyperelasticity.

International Journal of Solids and Structures. 42(23):6015-6031.

Murphy, J. (2013).

Transversely isotropic biological, soft tissue must be modelled using both anisotropic invariants. European Journal of Mechanics - A/Solids, 42:90–96.

Pucci, E. and Saccomandi, G. (2014).

On the use of universal relations in the modeling of transversely isotropic materials.

International Journal of Solids and Structures, 51(2):377–380.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

Van Loocke, M., Lyons, C., and Simms, C. (2006). A validated model of passive muscle in compression. *Journal of Biomechanics*, 39:29993009.